Interface Electronics



Peter Göttlicher DESY-FEB

DESY, November 12th 2015





Outline



- > Status of boards, numbers available
- > Number of boards
- > Status of firmware(µC)
- > Integration



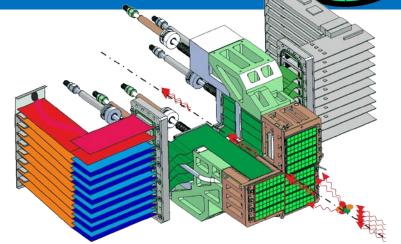
Status of analogue boards

Analogue mother board:

- 3 in hand with old gain
- 17 in hand with up-to-date gain

Analogue daughter

- 23 in hand
- 2 slot backplanes 12 in hand (basic tests)
- 8 slot backplanes 7 in hand



- Missing I2C power pull-down Just now adapter PCB in hand.
- Soldered to be ON w/o I2C

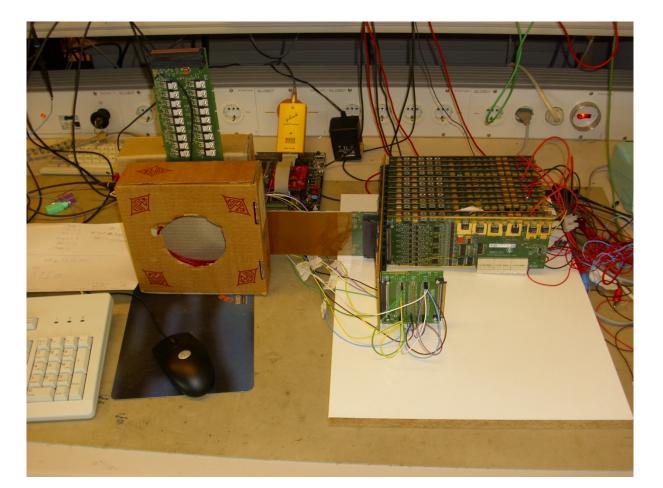
Questions to needs not answered!

Analogue mother in production for 2. and 3. 1mega-pixel with modified layout



... but typical intermittent usage







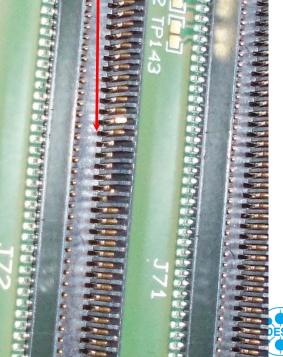
... but damages





2 of 7 backplanes are damaged

- Repairable
- But how does it happen?
- Both damages are a group of pins
 Worry: If that happens in system, it will be major work!
- Is it just because of no rails?
- Was there something in between?



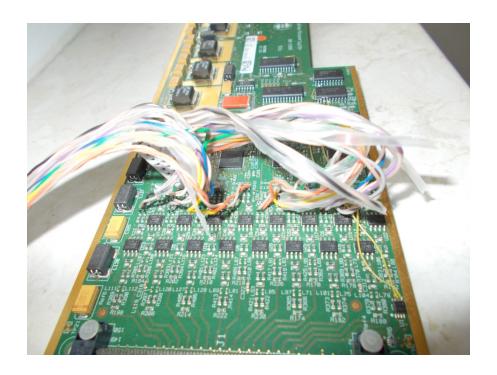
... but risky



Heavy force to solder pads.

Should not go to usage with hard access

How many looks like that?



Useful for test stands, firmware development

Be more careful, watch and tell how things happen, return damaged boards

→ I will look into getting things repaired





All field busses are operational Branch structure for I2C can be handled

Structured sensor tables are prepared

analogue board/vacuum boards, digital not yet

→Need command installation to transfer them to Ethernet

At the moment:

- Everything soldered, that the modules get to default state
- Communication to central FPGA not via SPI, but direct Ethernet.
 need of work at µC and FPGA

Karabo: They want to reactivate discussions soon. Since June they know, that LED's are switchable.



Common format for all levels: Karabo to µC



Command-counter:	32 bits	To follow losses and correlate answers
Command-ID	32 bits	x00000000 after long break as reset of command register ? x00000001 – x7FFFFFF by KARABO, kept within answer x80000001 – xFFFFFFF by μ C self generated Telling what to do
		 3 bit command level - Level 1: generic field-bus of μC - Level 2: generic field-bus of sensor/actor in branch-structure - Level 3: addressing by sensor/actor - Level 4: Full procedure
Address of fieldbus	32 bit	different levels
Address of sensor-location 64 bit different bits representing the module topology		
Number of data words Data words Consistency check	32 bit n ×32 b 32 bit	it Full data stream to field-bus

 \rightarrow Minor re-discussions while μ C-programming, up to now kept.





5 boards in hand, some bug fixes modified, 2 needed for 1 Mega-Pixel 12 SOM's in hand

- Some hardware bugs found, fixed by wiring
- Fan control and monitor not yet tested. Which fans?



Integration



Mechanic Integration: Many discussion over last months

- Mechanical integration
- EMI : Is all metal (mechanics) following, even informed?
- Fans, cooling
- Connectors
- → I expect, that is will take time also in the future

→ Seams a lot of open work

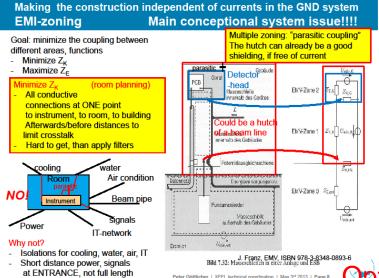
I am not sure, whether all information are exchanged Need to changes to interface?

Integration to Karabo: Much own µC work also preparation on KARABO-side before first µC connection.

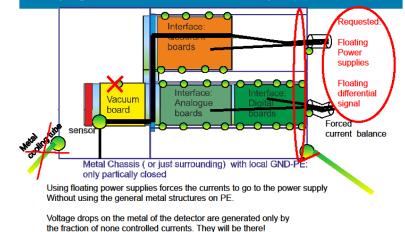




Replication.... News to grounding in hutches



Keeping GND free of currents: AGIPD-plans



M

⇒ They don't generate currents within the external metal PE system.

options from our electronics Peter Gotticher | XPEL technical coordination | I Peter Gotticher | XPEL technical coordination | I

The concept for industrial side planning is unlikely to be used for the XFEL-hutch planning: "It is task of experiment to get itself independent"

- Guided return currents with limited flow in PE-system
- Local current returns of parasitic currents to PE with option to open.
- Differential signaling
- But everything is limited and not perfect
 > Doing now a mechanical/electrical concept
 to have low impact from and to others is
 realistic, later changes even for studies are
 major efforts.

